

Transversals in groups. 4. Derivation construction

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Abstract

In the present work the derivation construction is studied by means of transversals in a group to a proper subgroup. It is shown that the method of derivation may be understood as a connection between different transversals in a group to a subgroup.

1. Introduction

The method of derivation has appeared in Dickson's works at the first time. It has been used to construct nearfields and quasifields from fields and skew-fields (see [14], [15]). Karzel [6] axiomatized and generalized this method for groups. Kiechle [7] gave a generalization of method of derivation which applied to construct loops with determined conditions by the help of groups.

In a present work the derivation construction is studied by means of transversals in a group to a proper subgroup. It is shown that the method of derivation may be understood as a connection between different transversals in a group to a subgroup. It give us a possibility to generalize the derivation construction for loops, i.e. to construct loops with some determined conditions by the help of some "good" loops.

2. Necessary definitions and notations

Definition 1. [2] A system $\langle E, \cdot \rangle$ is called a *right (left) quasigroup*, if for arbitrary $a, b \in E$ the equation $x \cdot a = b$ ($a \cdot y = b$) has a unique solution in the set E . If in quasigroup $\langle E, \cdot \rangle$ there exists element $e \in E$ such that

$$x \cdot e = e \cdot x = e$$

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for every $x \in E$, then system $\langle E, \cdot \rangle$ is called a *loop*.

Definition 2. [1] Let G be a group and H be a subgroup in G . A complete system $T = \{t_i\}_{i \in E}$ of representatives of the left (right) cosets of H in G ($e = t_1 \in H$) is called a *left (right) transversal in G to H* .

Let $T = \{t_i\}_{i \in E}$ be a left transversal in G to H . We can define correctly (see [1, 9]) the following operation on the set E (E is an index set; left cosets of H in G are numbered by indexes from E):

$$x \stackrel{(T)}{\cdot} y = z \iff \text{def} \quad t_x t_y = t_z h, \quad h \in H. \quad (1)$$

In [1] (and [9]) it is proved that $\langle E, \stackrel{(T)}{\cdot} \rangle$ is a left quasigroup with two-sided unit 1.

Below we shall consider (for simplicity) that $\text{Core}_G(H) = e$ (where

$$\text{Core}_G(H) = \bigcap_{g \in G} gHg^{-1}$$

is the maximal normal subgroup of the group G contained in the subgroup H) and shall study a permutation representation \hat{G} of group G by left cosets on the subgroup H . According to [5], we have $\hat{G} \cong G$, where

$$\hat{g}(x) = y \iff \text{def} \quad gt_x H = t_y H.$$

Note that $\hat{H} = St_1(\hat{G})$.

Lemma 1. ([9], Lemma 4) *Let T be an arbitrary left transversal in G to H . Then the following statements are true:*

1. $\hat{h}(1) = 1$ for all $h \in H$.
2. For every $x, y \in E$ we have: $\hat{t}_x(y) = x \stackrel{(T)}{\cdot} y$, $\hat{t}_1(x) = \hat{t}_x(1) = x$,
 $\hat{t}_x^{-1}(y) = x \setminus y$, $\hat{t}_x^{-1}(1) = x \setminus 1$, $\hat{t}_x^{-1}(x) = 1$

where \setminus is the left division in the system $\langle E, \stackrel{(T)}{\cdot}, 1 \rangle$

(i.e. $x \setminus y = z \iff x \stackrel{(T)}{\cdot} z = y$). □

Let us denote

$$l_{a,b}^{(T)} = L_{a \stackrel{(T)}{\cdot} b}^{-1} L_a L_b$$

where $L_a(x) = a \overset{(T)}{\cdot} x$ is a left translation in the left loop $\langle E, \overset{(T)}{\cdot}, 1 \rangle$. The group

$$LI(\langle E, \overset{(T)}{\cdot}, 1 \rangle) = \langle l_{a,b}^{(T)} \mid a, b \in E \rangle$$

is called a *left inner permutation group*. It is easy to see that

$$l_{a,b}^{(T)}(x) = (a \overset{(T)}{\cdot} b) \overset{(T)}{\setminus} (a \overset{(T)}{\cdot} (b \overset{(T)}{\cdot} x)) = \hat{t}_{a \overset{(T)}{\cdot} b}^{-1} \hat{t}_a \hat{t}_b(x). \quad (2)$$

Note that for every $a, b \in E$ $l_{a,b}^{(T)}(1) = 1$.

Definition 3. A left loop $\langle E, \cdot, 1 \rangle$ is called

1. *left alternative*, if for every $x, y \in E$: $x \cdot (x \cdot y) = (x \cdot x) \cdot y$,
2. *left IP-loop* (or *LIP-loop*), if for every $x \in E$ there exists the element $x' \in E$ such that $x' \cdot (x \cdot y) = y$ for every $y \in E$,
3. *left A_l -loop*, if for every $a, b \in E$ $l_{a,b} \in \text{Aut}(\langle E, \cdot, 1 \rangle)$.

Lemma 2. Let a set $T = \{t_i\}_{i \in E}$ be a left transversal in the group G to its subgroup H . Then the following conditions are equivalent:

1. The system $\langle E, \overset{(T)}{\cdot}, 1 \rangle$ is a left A_l -loop,
2. For every $\alpha \in LI(\langle E, \overset{(T)}{\cdot}, 1 \rangle)$ we have $\alpha \hat{T} \alpha^{-1} \subseteq \hat{T}$.

Proof. 1 \implies 2. Let the system $\langle E, \overset{(T)}{\cdot}, 1 \rangle$ be a left A_l -loop, i.e. let

$$l_{a,b}^{(T)} = \hat{t}_{a \overset{(T)}{\cdot} b}^{-1} \hat{t}_a \hat{t}_b \in \text{Aut}(\langle E, \overset{(T)}{\cdot}, 1 \rangle)$$

for every $a, b \in E$. Then

$$LI(\langle E, \overset{(T)}{\cdot}, 1 \rangle) \subseteq \text{Aut}(\langle E, \overset{(T)}{\cdot}, 1 \rangle). \quad (3)$$

Let $\alpha \in LI(\langle E, \overset{(T)}{\cdot}, 1 \rangle)$. Because $\alpha \hat{t}_x \alpha^{-1} \in \hat{G}$ for every $x \in E$, then

$$\alpha \hat{t}_x \alpha^{-1} = \hat{t}_u \hat{h}_1 \quad (4)$$

for some $u \in E$ and $h_1 \in H$. In view of Lemma 1 we have

$$u = \hat{t}_u(1) = \hat{t}_u \hat{h}_1(1) = \alpha \hat{t}_x \alpha^{-1}(1) = \alpha \hat{t}_x(1) = \alpha(x),$$

i.e. the equation (4) may be rewritten in the following form

$$\alpha \hat{t}_x \alpha^{-1} = \hat{t}_{\alpha(x)} \hat{h}_1. \quad (5)$$

On the other hand, for every $x, y \in E$

$$\hat{t}_x \hat{t}_y = \hat{t}_{x \cdot y} l_{x,y}^{(T)},$$

$$\alpha \hat{t}_x \alpha^{-1} \alpha \hat{t}_y \alpha^{-1} = \alpha \hat{t}_{x \cdot y} \alpha^{-1} \alpha l_{x,y}^{(T)} \alpha^{-1},$$

which, by (5), gives

$$\hat{t}_{\alpha(x)} \hat{h}_1 \hat{t}_{\alpha(y)} \hat{h}_2 = \hat{t}_{\alpha(x \cdot y)} \hat{h}_3 \alpha l_{x,y}^{(T)} \alpha^{-1}$$

for some $h_2, h_3 \in H$. In view of Lemma 1 we have also

$$\hat{t}_{\alpha(x)} \hat{h}_1 \hat{t}_{\alpha(y)} \hat{h}_2(1) = \hat{t}_{\alpha(x \cdot y)} \hat{h}_3 \alpha l_{x,y}^{(T)} \alpha^{-1}(1),$$

$$\alpha(x) \cdot \hat{h}_1(\alpha(y)) = \alpha(x \cdot y). \quad (6)$$

But $\alpha \in LI(\langle E, \cdot, 1 \rangle)$. Thus, by (3), we have $\alpha(x \cdot y) = \alpha(x) \cdot \alpha(y)$. So, by (6), we obtain:

$$\alpha(x) \cdot \hat{h}_1(\alpha(y)) = \alpha(x) \cdot \alpha(y)$$

for every $x, y \in E$. Since the system $\langle E, \cdot, 1 \rangle$ is a left quasigroup with two-sided unit 1, for every $y \in E$ we get

$$\hat{h}_1(\alpha(y)) = \alpha(y).$$

Function α is a permutation on the set E , so for every $z \in E$ $\hat{h}_1(z) = z$, i.e. $h_1 = e$. Then in view of (5) we obtain:

$$\alpha \hat{t}_x \alpha^{-1} = \hat{t}_{\alpha(x)} \in \hat{T} \quad (7)$$

for every $\alpha \in LI(\langle E, \cdot, 1 \rangle)$ and $x \in E$.

2 \implies 1. (See [8]) Let for every $\alpha \in LI(\langle E, \cdot, 1 \rangle)$ and $x \in E$ exists an element $u \in E$ such that

$$\alpha \hat{t}_x \alpha^{-1} = \hat{t}_u \in \hat{T}. \quad (8)$$

Then, in view of Lemma 1, we have

$$u = \hat{t}_u(1) = \alpha \hat{t}_x \alpha^{-1}(1) = \alpha \hat{t}_x(1) = \alpha(x),$$

i.e. the equation (8) may be rewritten in the following way

$$\alpha \hat{t}_x \alpha^{-1} = \hat{t}_{\alpha(x)}. \quad (9)$$

But every $x, y \in E$ we have

$$\hat{t}_x \hat{t}_y = \hat{t}_{x \cdot^{(T)} y} l_{x,y}^{(T)}.$$

Then

$$\alpha \hat{t}_x \alpha^{-1} \alpha \hat{t}_y \alpha^{-1} = \alpha \hat{t}_{x \cdot^{(T)} y} \alpha^{-1} \alpha l_{x,y}^{(T)} \alpha^{-1},$$

which, by (9), gives

$$\hat{t}_{\alpha(x)} \hat{t}_{\alpha(y)} = \hat{t}_{\alpha(x \cdot^{(T)} y)} \alpha l_{x,y}^{(T)} \alpha^{-1}$$

and, in the consequence,

$$\alpha l_{x,y}^{(T)} \alpha^{-1} \in LI(\langle E, \cdot^{(T)}, 1 \rangle) \subseteq \hat{H},$$

because $\alpha, l_{x,y}^{(T)} \in LI(\langle E, \cdot^{(T)}, 1 \rangle)$. Now, applying the definition of the left transversal T , we obtain

$$\alpha(x) \cdot^{(T)} \alpha(y) = \alpha(x \cdot^{(T)} y).$$

This means that $\alpha \in \text{Aut}(\langle E, \cdot^{(T)}, 1 \rangle)$ and $\langle E, \cdot^{(T)}, 1 \rangle$ is a left A_l -loop. \square

Lemma 3. *Let $\langle E, \cdot, 1 \rangle$ be a left loop. Then the following statements are true:*

1. *System $\langle E, \cdot, 1 \rangle$ is LIP-loop if and only if for every $a \in E$: if $a \cdot a' = 1$ for some $a' \in E$ then $l_{a,a'} = id$.*
2. *System $\langle E, \cdot, 1 \rangle$ is left alternative if and only if $l_{a,a} = id$ for every $a \in E$.*

Proof. See [7]. \square

3. Derivation as a connection between transversals in a group by the same subgroup

Let us remind the general method of derivation used for construction of loops [7], section 7.

Let $\langle A, \cdot, 1 \rangle$ be a group. The function $\varphi : A \rightarrow S_A$ such that $\varphi(a) \rightleftharpoons \varphi_a$, $\varphi_1 = id$ and $\varphi_a(1) = 1$ for any $a \in A$ is called a *weak derivation*. It is called a *derivation* if furthermore for all $a, b \in A$ there exists a unique $x \in A$ such that $x \cdot \varphi_x(a) = b$.

In [7], section 7, it was proved the following

Lemma 4. *Let $\langle A, \cdot, 1 \rangle$ be a group with a weak derivation φ . Let us define the operation*

$$x \circ y \stackrel{def}{=} x \cdot \varphi_x(y). \quad (10)$$

Then:

1. *The system $\langle A, \circ, 1 \rangle$ is a left loop with two-sided unit 1 (the identity elements of $\langle A, \cdot, 1 \rangle$ and $\langle A, \circ, 1 \rangle$ coincide). Moreover, for all $a \in A$ if $a \circ a' = 1$, then $a' = \varphi_a^{-1}(a^{-1})$.*
2. *If φ is a derivation, then system $\langle A, \circ, 1 \rangle$ is a loop.*

The system $\langle A, \circ, 1 \rangle$ is called a *derived (left) loop*. If $\varphi_a \in Aut A$ for every $a \in A$, then derivation is called *automorphic derivation*.

For the connection between two different left transversals in a group G by the same subgroup H see [9, 10].

Let $T = \{t_x\}_{x \in E}$ and $P = \{p_x\}_{x \in E}$ are two left transversals in a group G to its subgroup H . It is evident that for every $x \in E$ $p_x = t_x h_{(x)}$ for some collection $\{h_{(x)}\}_{x \in E}$, $h_{(x)} \in H$. As it was proved in [9], for systems $\langle E, \overset{(T)}{\cdot}, 1 \rangle$ and $\langle E, \overset{(P)}{\cdot}, 1 \rangle$ corresponding to the transversals T and P , by formula (1), we have:

$$x \overset{(P)}{\cdot} y = x \overset{(T)}{\cdot} \hat{h}_{(x)}(y). \quad (11)$$

It is easy to see that formulas (10) and (11) almost coincide; moreover, $\hat{h}_{(1)} = id$ and $\hat{h}_{(x)}(1) = 1$ for every $x \in E$. Note that unlike the derivation construction described above the system $\langle E, \overset{(T)}{\cdot}, 1 \rangle$ is not a group; in a general case it is a left loop with two-sided unit. This means that the construction of new operations by the help of the connection between different left transversals in a group G to its subgroup H (formula (11)) generalize the derivation method (formula (10)). So the construction of weak derivation from formula (10) may be generalized up to the class of left loops which

are corresponding to the left transversals in a some group G to its subgroup H . The system $\langle E, \overset{(P)}{\cdot}, 1 \rangle$ from formula (11) will be called *derived left loop* and the set of permutations $\{\hat{h}_{(x)}\}_{x \in E}$ will be called a *deriving set*.

Lemma 5. *Let $\langle E, \overset{(P)}{\cdot}, 1 \rangle$ be a derived left loop obtained by the method of weak derivation (formula (11)) from the left loop $\langle E, \overset{(T)}{\cdot}, 1 \rangle$ by the help of derived set $\{\hat{h}_{(x)}\}_{x \in E}$. Then the following sentences are true:*

1. *Two-sided units of the left loops $\langle E, \overset{(P)}{\cdot}, 1 \rangle$ and $\langle E, \overset{(T)}{\cdot}, 1 \rangle$ coincide.*
2. *If a^{-1} is a right inverse to the element a in $\langle E, \overset{(P)}{\cdot}, 1 \rangle$, then $a^{-1} = \hat{h}_{(a)}^{-1}(a^{-1})$, where a^{-1} is a right inverse to the element a in $\langle E, \overset{(T)}{\cdot}, 1 \rangle$.*
3. *The left loop $\langle E, \overset{(P)}{\cdot}, 1 \rangle$ is a loop (i.e. weak derivation is a derivation) if and only if the operations $\langle E, \overset{(T)}{\cdot}, 1 \rangle$ and $B(x, y) = \hat{h}_{(x)}^{-1}(y)$ are orthogonal.*

Proof. 1. It is easy to see that if 1 is a unit in $\langle E, \overset{(T)}{\cdot}, 1 \rangle$, then

$$\begin{aligned} 1 \overset{(P)}{\cdot} x &= 1 \overset{(T)}{\cdot} \hat{h}_{(1)}(x) = 1 \overset{(T)}{\cdot} x = x, \\ x \overset{(P)}{\cdot} 1 &= x \overset{(T)}{\cdot} \hat{h}_{(x)}(1) = x \overset{(T)}{\cdot} 1 = x. \end{aligned}$$

2. If a^{-1} is a right inverse to a in $\langle E, \overset{(P)}{\cdot}, 1 \rangle$, then $a \overset{(P)}{\cdot} a^{-1} = 1$. Thus $a \overset{(T)}{\cdot} \hat{h}_{(a)}(a^{-1}) = 1$ and $a^{-1} = \hat{h}_{(a)}^{-1}(a^{-1})$.

3. (See also [3], [10]) It is enough to prove that the equation $x \overset{(P)}{\cdot} a = b$ has a unique solution in E for any fixed $a, b \in E$ if and only if the operations $\langle E, \overset{(T)}{\cdot}, 1 \rangle$ and $B(x, y) = \hat{h}_{(x)}^{-1}(y)$ are orthogonal, i.e. if and only if the system

$$\begin{cases} x \overset{(T)}{\cdot} y = a \\ B(x, y) = b \end{cases}$$

has a unique solution in the set $E \times E$ for any $a, b \in E$.

We have

$$\begin{cases} x \overset{(P)}{\cdot} a = b \\ x \overset{(T)}{\cdot} \hat{h}_{(x)}(a) = b \end{cases} \iff \begin{cases} \hat{h}_{(x)}(a) = z \\ x \overset{(T)}{\cdot} z = b \end{cases} \iff$$

$$\iff \left\{ \begin{array}{l} \hat{h}_{(x)}^{-1}(z) = a \\ x \cdot^{(T)} z = b \end{array} \right. \iff \left\{ \begin{array}{l} B(x, z) = a \\ x \cdot^{(T)} z = b \end{array} \right.$$

Last system has a unique solution if and only if the operations $\langle E, \cdot^{(T)}, 1 \rangle$ and $B(x, y) = \hat{h}_{(x)}^{-1}(y)$ are orthogonal. \square

Remark 1. According to Cayley's Theorem (see [5], theorem 12.1.1, 12.1.3) every group K may be represented as a permutation group on the set K ; this representation is regular. So any group K may be represented as a group transversal in S_K to $St_1(S_K)$. Then the construction of weak derivation of an arbitrary group $\langle A, \cdot, 1 \rangle$ to the derived left loop $\langle A, \circ, 1 \rangle$ may be represented as a construction of the left transversal $P = \{p_x\}_{x \in E}$ in the group S_A to $St_1(S_A)$ by the help of the group transversal $A^* = \{t_x\}_{x \in E}$ in the group S_A to $St_1(S_A)$. The corresponding system $\langle E, \cdot^{(A)}, 1 \rangle$ is isomorphic to the group $\langle A, \cdot, 1 \rangle$ and the system $\langle E, \cdot^{(P)}, 1 \rangle$ is isomorphic to the derived left loop $\langle A, \circ, 1 \rangle$.

Remark 2. The construction of weak derivation may also take place when there exists a group transversal T in the group G to its subgroup H . Then any other left transversal P in the group G to its subgroup H may be represented as a weak derivation of the group transversal T by the help of the deriving set $\{\hat{h}_{(x)}\}_{x \in E} \subset \hat{H}$.

Remark 3. The construction of automorphic derivation may be naturally represented as a connection between left transversals in the group G to its subgroup H , where G is a semidirect product (see [13], [11]) of a left loop $\langle E, \cdot, 1 \rangle$ and group H , and $LI(\langle E, \cdot, 1 \rangle) \subseteq H \subseteq Aut(\langle E, \cdot, 1 \rangle)$.

4. Automorphic derivations

Let us investigate the case of weak automorphic derivation of left loops, i.e. the case of weak derivation with the condition

$$\{\hat{h}_{(x)}\}_{x \in E} \subseteq Aut(\langle E, \cdot, 1 \rangle).$$

Lemma 6. *Let $\langle E, \cdot^{(P)}, 1 \rangle$ be a derived left loop, which is obtained from a left loop $\langle E, \cdot^{(T)}, 1 \rangle$ by means of weak automorphic derivation by the help of the deriving set $\{\hat{h}_{(x)}\}_{x \in E}$. We have*

1. *The following conditions are equivalent:*

- (a) $\alpha \in \text{Aut}(\langle E, \overset{(T)}{\cdot}, 1 \rangle)$ is an automorphism of $\langle E, \overset{(P)}{\cdot}, 1 \rangle$,
- (b) $\alpha \hat{h}_{(x)} \alpha^{-1} = \hat{h}_{(\alpha(x))}$ for every $x \in E$,
- (c) $\alpha \in \text{Aut}(\langle E, \overset{(P)}{\cdot}, 1 \rangle)$ is an automorphism of $\langle E, \overset{(T)}{\cdot}, 1 \rangle$.
2. $l_{a,b}^{(P)} = \hat{h}_{(a \overset{(P)}{\cdot} b)}^{-1} l_{a, \hat{h}_{(a)}(b)}^{(T)} \hat{h}_{(a)} \hat{h}_{(b)}$ for every $a, b \in E$,
3. The system $\langle E, \overset{(P)}{\cdot}, 1 \rangle$ is left alternative if and only if for every $a \in E$
- $$\hat{h}_{(a \overset{(P)}{\cdot} a)} = l_{a, \hat{h}_{(a)}(a)}^{(T)} \hat{h}_{(a)}^2.$$
4. The system $\langle E, \overset{(P)}{\cdot}, 1 \rangle$ is a LIP-loop if and only if for every $a \in E$
- $$\hat{h}_{(a)}^{-1} = \hat{h}_{(\hat{h}_{(a)}^{-1}(a'))} l_{a, a'}^{(T)}, \quad \text{where } a' = a^{-1}.$$
5. The system $\langle E, \overset{(P)}{\cdot}, 1 \rangle$ is a left Bol loop if and only if for every $a, b \in E$
- $$\hat{h}_{(a \overset{(P)}{\cdot} (b \overset{(P)}{\cdot} a))} = l_{a, \hat{h}_{(a)}(b \overset{(P)}{\cdot} a)}^{(T)} \hat{h}_{(a)} l_{b, \hat{h}_{(b)}(a)}^{(T)} \hat{h}_{(b)} \hat{h}_{(a)}.$$
6. The system $\langle E, \overset{(P)}{\cdot}, 1 \rangle$ is a group if and only if for every $a, b \in E$
- $$\hat{h}_{(a \overset{(P)}{\cdot} b)} = l_{a, \hat{h}_{(a)}(b)}^{(T)} \hat{h}_{(a)} \hat{h}_{(b)}.$$

Proof. 1. (a) \iff (b). If $\alpha \in \text{Aut}(\langle E, \overset{(T)}{\cdot}, 1 \rangle)$, we have for every $x, y \in E$

$$\begin{aligned} \alpha(x) \overset{(P)}{\cdot} \alpha(y) &= \alpha(x \overset{(P)}{\cdot} y), \\ \alpha(x) \overset{(T)}{\cdot} \hat{h}_{(\alpha(x))} \alpha(y) &= \alpha(x \overset{(T)}{\cdot} \hat{h}_{(x)}(y)) = \alpha(x) \overset{(T)}{\cdot} \alpha \hat{h}_{(x)}(y), \\ \hat{h}_{(\alpha(x))} \alpha(y) &= \alpha \hat{h}_{(x)}(y), \\ \hat{h}_{(\alpha(x))} &= \alpha \hat{h}_{(x)} \alpha^{-1}. \end{aligned}$$

(c) \iff (b). For every $x, y \in E$ we have $x \overset{(T)}{\cdot} y = x \overset{(P)}{\cdot} \hat{h}_{(x)}^{-1}(y)$. So the result follows as before.

2. Because of $\hat{h}_{(a)} \in \text{Aut}(\langle E, \overset{(T)}{\cdot}, 1 \rangle)$ for every $a \in E$, so we have for every $a, b, x \in E$

$$\begin{aligned} a \overset{(P)}{\cdot} (b \overset{(P)}{\cdot} x) &= (a \overset{(P)}{\cdot} b) \overset{(P)}{\cdot} l_{a,b}^{(P)}(x), \\ a \overset{(T)}{\cdot} \hat{h}_{(a)}(b \overset{(T)}{\cdot} \hat{h}_{(b)}(x)) &= (a \overset{(T)}{\cdot} \hat{h}_{(a)}(b)) \overset{(T)}{\cdot} \hat{h}_{(a \overset{(P)}{\cdot} b)} l_{a,b}^{(P)}(x), \\ a \overset{(T)}{\cdot} (\hat{h}_{(a)}(b) \overset{(T)}{\cdot} \hat{h}_{(a)} \hat{h}_{(b)}(x)) &= (a \overset{(T)}{\cdot} \hat{h}_{(a)}(b)) \overset{(T)}{\cdot} \hat{h}_{(a \overset{(P)}{\cdot} b)} l_{a,b}^{(P)}(x), \end{aligned}$$

$$(a \overset{(T)}{\cdot} \hat{h}_{(a)}(b)) \overset{(T)}{\setminus} (a \overset{(T)}{\cdot} (\hat{h}_{(a)}(b) \overset{(T)}{\cdot} \hat{h}_{(a)}\hat{h}_{(b)}(x))) = \hat{h}_{(a \overset{(P)}{\cdot} b)} l_{a,b}^{(P)}(x).$$

In view of formula (2) we obtain for every $x \in E$

$$\begin{aligned} l_{a, \hat{h}_{(a)}(b)}^{(T)} \hat{h}_{(a)}\hat{h}_{(b)}(x) &= \hat{h}_{(a \overset{(P)}{\cdot} b)} l_{a,b}^{(P)}(x), \\ l_{a,b}^{(P)} &= \hat{h}_{(a \overset{(P)}{\cdot} b)}^{-1} l_{a, \hat{h}_{(a)}(b)}^{(T)} \hat{h}_{(a)}\hat{h}_{(b)}. \end{aligned}$$

3. According to Lemma 3 the system $\langle E, \overset{(P)}{\cdot}, 1 \rangle$ is left alternative if and only if $l_{a,a}^{(P)} = id$ for every $a \in E$. So by the condition 2) the result follows.

4. According to Lemma 3 the system $\langle E, \overset{(P)}{\cdot}, 1 \rangle$ is a LIP-loop if and only if for every $a \in E$: if $a \overset{(P)}{\cdot} a'' = 1$ for some $a'' \in E$, then $l_{a,a''}^{(P)} = id$. So in view of the proposition 2) of present Lemma we obtain

$$id = \hat{h}_{(a \overset{(P)}{\cdot} a'')}^{-1} l_{a, \hat{h}_{(a)}(a'')}^{(T)} \hat{h}_{(a)}\hat{h}_{(a'')} = l_{a, \hat{h}_{(a)}(a'')}^{(T)} \hat{h}_{(a)}\hat{h}_{(a'')}.$$

Because of $a'' = \hat{h}_{(a)}^{-1}(a^{-1})$, then $\hat{h}_{(a)}^{-1} = \hat{h}_{(\hat{h}_{(a)}^{-1}(a''))} l_{a,a''}^{(T)}$, where $a''' = a^{-1}$.

5. It is easy to prove (see [7]) that the left Bol identity

$$(a \overset{(P)}{\cdot} (b \overset{(P)}{\cdot} a) \overset{(P)}{\cdot} x) = a \overset{(P)}{\cdot} (b \overset{(P)}{\cdot} (a \overset{(P)}{\cdot} x))$$

for every $a, b, x \in E$ is equivalent to the identity $l_{a, b \overset{(P)}{\cdot} a}^{(P)} = (l_{b,a}^{(P)})^{-1}$ for every $a, b \in E$. So in view of the condition 2) of the present Lemma we obtain

$$\begin{aligned} \hat{h}_{(a \overset{(P)}{\cdot} (b \overset{(P)}{\cdot} a))}^{-1} l_{a, \hat{h}_{(a)}(b \overset{(P)}{\cdot} a)}^{(T)} \hat{h}_{(a)}\hat{h}_{(b \overset{(P)}{\cdot} a)} &= \hat{h}_{(a)}^{-1} \hat{h}_{(b \overset{(P)}{\cdot} a)}^{-1} l_{b, \hat{h}_{(b)}(a)}^{(T)-1} \hat{h}_{(b \overset{(P)}{\cdot} a)}, \\ \hat{h}_{(a \overset{(P)}{\cdot} (b \overset{(P)}{\cdot} a))} &= l_{a, \hat{h}_{(a)}(b \overset{(P)}{\cdot} a)}^{(T)} \hat{h}_{(a)} l_{b, \hat{h}_{(b)}(a)}^{(T)} \hat{h}_{(b)}\hat{h}_{(a)}. \end{aligned}$$

6. It is easy to prove that system $\langle E, \overset{(P)}{\cdot}, 1 \rangle$ is a group if and only if $l_{a,b}^{(P)} = id$ for every $a, b \in E$. So in view of the condition 2) of present Lemma we obtain the result. \square

Corollary 1. *Let the general assumptions of Lemma 6 hold. If the system $\langle E, \overset{(P)}{\cdot}, 1 \rangle$ is a group, then the system $\langle E, \overset{(T)}{\cdot}, 1 \rangle$ is an A_1 -loop.*

Proof. In view of proposition 6) of Lemma 6 if the system $\langle E, \overset{(P)}{\cdot}, 1 \rangle$ is a group then $\hat{h}_{(a \overset{(P)}{\cdot} b)} = l_{a, \hat{h}_{(a)}(b)}^{(T)} \hat{h}_{(a)} \hat{h}_{(b)}$. Because of $\hat{h}_{(a)} \in \text{Aut}(\langle E, \overset{(T)}{\cdot}, 1 \rangle)$ for every $a \in E$, then $l_{a, \hat{h}_{(a)}(b)}^{(T)} \in \text{Aut}(\langle E, \overset{(T)}{\cdot}, 1 \rangle)$ for every $a, b \in E$. But $\hat{h}_{(a)}$ is a permutation on the set E for every $a \in E$, then $l_{a, c}^{(T)} \in \text{Aut}(\langle E, \overset{(T)}{\cdot}, 1 \rangle)$ for every $a, c \in E$. So $\langle E, \overset{(T)}{\cdot}, 1 \rangle$ is an A_l -loop. \square

4.1. An automorphic derivation of group

Let us apply the previous lemma to the case when $\langle E, \overset{(T)}{\cdot}, 1 \rangle$ is a group.

Lemma 7. (See [7]) *Let $\langle E, \overset{(P)}{\cdot}, 1 \rangle$ be a derived left loop, which is obtained from a group $\langle E, \overset{(T)}{\cdot}, 1 \rangle$ by means of weak automorphic derivation by the help of deriving set $\{\hat{h}_{(x)}\}_{x \in E}$. Then the following statements are true:*

1. *The following conditions are equivalent:*
 - (a) $\alpha \in \text{Aut}(\langle E, \overset{(T)}{\cdot}, 1 \rangle)$ is an automorphism of $\langle E, \overset{(P)}{\cdot}, 1 \rangle$,
 - (b) $\alpha \hat{h}_{(x)} \alpha^{-1} = \hat{h}_{(\alpha(x))}$ for every $x \in E$,
 - (c) $\alpha \in \text{Aut}(\langle E, \overset{(P)}{\cdot}, 1 \rangle)$ is an automorphism of the operation $\langle E, \overset{(T)}{\cdot}, 1 \rangle$.
2. $l_{a, b}^{(P)} = \hat{h}_{(a \overset{(P)}{\cdot} b)}^{-1} \hat{h}_{(a)} \hat{h}_{(b)} \in \text{Aut}(\langle E, \overset{(T)}{\cdot}, 1 \rangle)$ for every $a, b \in E$,
3. *The system $\langle E, \overset{(P)}{\cdot}, 1 \rangle$ is left alternative if and only if for every $a \in E$*

$$\hat{h}_{(a \overset{(P)}{\cdot} a)} = \hat{h}_{(a)}^2.$$

4. *The system $\langle E, \overset{(P)}{\cdot}, 1 \rangle$ is LIP-loop if and only if for every $a \in E$*

$$\hat{h}_{(a)}^{-1} = \hat{h}_{(\hat{h}_{(a)}^{-1}(a'))}, \text{ where } a' = a^{-1}.$$

5. *The system $\langle E, \overset{(P)}{\cdot}, 1 \rangle$ is a left Bol loop if and only if for every $a, b \in E$*

$$\hat{h}_{(a \overset{(P)}{\cdot} (b \overset{(P)}{\cdot} a))} = \hat{h}_{(a)} \hat{h}_{(b)} \hat{h}_{(a)}.$$

6. *The system $\langle E, \overset{(P)}{\cdot}, 1 \rangle$ is a group if and only if for every $a, b \in E$*

$$\hat{h}_{(a \overset{(P)}{\cdot} b)} = \hat{h}_{(a)} \hat{h}_{(b)}.$$

Proof. It is the evident corollary of Lemma 6, because $l_{a, b}^{(T)} = id$ for every $a, b \in E$, if the system $\langle E, \overset{(T)}{\cdot}, 1 \rangle$ is a group. See also [7]. \square

Corollary 2. *Let the conditions of Lemma 7 hold. If for every $h \in H$ we have $hh_{(x)}h^{-1} = h_{(\hat{h}(x))}$, then the system $\langle E, \overset{(P)}{\cdot}, 1 \rangle$ is an A_l -loop.*

Proof. It is evident because $LI(\langle E, \overset{(P)}{\cdot}, 1 \rangle) \subseteq \hat{H}$ for every left transversal P in a group G to a subgroup H . \square

Corollary 3. (See [15]) *Let the conditions of Lemma 7 hold. If $\langle E, \overset{(P)}{\cdot}, 1 \rangle$ is a group, then $\langle H_{(*)}, \cdot, h_{(1)} \rangle$, where $H_{(*)} \rightleftharpoons \{h_{(x)} | x \in E\}$, is a subgroup of the group H .*

Proof. It is an evident corollary of 4) and 6) from Lemma 7. \square

4.2. An automorphic derivation of A_l -loop

Let us apply Lemma 6 in a case when $\langle E, \overset{(T)}{\cdot}, 1 \rangle$ is an A_l -loop.

Lemma 8. *Let $\langle E, \overset{(P)}{\cdot}, 1 \rangle$ be a derived left loop, which is obtained from the A_l -loop $\langle E, \overset{(T)}{\cdot}, 1 \rangle$ by means of weak automorphic derivation by the help of the deriving set $\{\hat{h}_{(x)}\}_{x \in E}$. Then:*

1. $l_{a,b}^{(P)} = \hat{h}_{(a)}^{-1} l_{a, \hat{h}_{(a)}(b)}^{(T)} \hat{h}_{(a)} \hat{h}_{(b)} \in \text{Aut}(\langle E, \overset{(T)}{\cdot}, 1 \rangle)$ for every $a, b \in E$,
2. $\langle E, \overset{(P)}{\cdot}, 1 \rangle$ is an A_l -loop if and only if for every $\alpha \in LI(\langle E, \overset{(P)}{\cdot}, 1 \rangle)$ we have $\alpha \hat{h}_{(x)} \alpha^{-1} = \hat{h}_{(\alpha(x))}$.

Proof. 1. Since the system $\langle E, \overset{(T)}{\cdot}, 1 \rangle$ is an A_l -loop, $l_{a,b}^{(T)} \in \text{Aut}(\langle E, \overset{(T)}{\cdot}, 1 \rangle)$ for every $a, b \in E$. But by the definition of a weak automorphic derivation $\hat{h}_{(x)} \in \text{Aut}(\langle E, \overset{(T)}{\cdot}, 1 \rangle)$ for every $x \in E$. Thus, by the condition 2) of Lemma 6, we obtain our thesis.

2. If $\langle E, \overset{(P)}{\cdot}, 1 \rangle$ is a A_l -loop, then in view of 1) from Lemma 6 and 1) from the present Lemma it is equivalent to $l_{a,b}^{(P)} \hat{h}_{(x)} l_{a,b}^{(P)-1} = \hat{h}_{(l_{a,b}^{(P)}(x))}$ for every $a, b \in E$. Since $LI(\langle E, \overset{(P)}{\cdot}, 1 \rangle) = \langle l_{a,b}^{(P)} | a, b \in E \rangle$, for every $\alpha \in LI(\langle E, \overset{(P)}{\cdot}, 1 \rangle)$ we obtain $\alpha \hat{h}_{(x)} \alpha^{-1} = \hat{h}_{(\alpha(x))}$. But according to the condition 2) of the present Lemma we have $LI(\langle E, \overset{(P)}{\cdot}, 1 \rangle) \subseteq \text{Aut}(\langle E, \overset{(T)}{\cdot}, 1 \rangle)$. \square

Corollary 4. Let $\langle E, \overset{(T)}{\cdot}, 1 \rangle$ be an A_l -loop and $G = LM(\langle E, \overset{(T)}{\cdot}, 1 \rangle)$ its left multiplication group. Then the system $\langle E, \overset{(P)}{\cdot}, 1 \rangle$ is an A_l -loop if and only if $\alpha h_{(x)} \alpha^{-1} = h_{(\alpha(x))}$ for every $\alpha \in LI(\langle E, \overset{(P)}{\cdot}, 1 \rangle)$.

Proof. Since the system $\langle E, \overset{(T)}{\cdot}, 1 \rangle$ is an A_l -loop and $H = LI(\langle E, \overset{(T)}{\cdot}, 1 \rangle)$, every element $h \in H$ is an automorphism of $\langle E, \overset{(T)}{\cdot}, 1 \rangle$. So in this case every weak derivation of the A_l -loop $\langle E, \overset{(T)}{\cdot}, 1 \rangle$ is an automorphic weak derivation. In view of the condition 2) of Lemma 8 we obtain the necessity. \square

Corollary 5. Let the conditions of Corollary 4 hold. If for every $h \in H$ we have $hh_{(x)}h^{-1} = h_{(h(x))}$, then the system $\langle E, \overset{(P)}{\cdot}, 1 \rangle$ is an A_l -loop.

Proof. It is a consequence of our Corollary 4, because $LI(\langle E, \overset{(P)}{\cdot}, 1 \rangle) \subseteq H$ for every left transversal P in a group G to a subgroup H . \square

Definition 4. A transversal T in the group G by its subgroup H is called a *gyrotransversal* if $T^{-1} = T$ and $hTh^{-1} \subseteq T$ for every $h \in H$.

Lemma 9. Let the set $T = \{t_x\}_{x \in E}$ be a gyrotransversal in the group G by the subgroup H . Then $ht_xh^{-1} = t_{\hat{h}(x)}$ and $t_x^{-1} = t_{x \setminus 1}$ for every $h \in H$, $x \in E$.

Proof. As the set $T = \{t_x\}_{x \in E}$ is a gyrotransversal in the group G by the subgroup H , so for every $h \in H$ we have $hTh^{-1} \subseteq T$, i.e. $ht_xh^{-1} = t_v$, where $v = \hat{t}_v(1) = \hat{h} \hat{t}_x \hat{h}^{-1}(1) = \hat{h} \hat{t}_x(1) = \hat{h}(x)$. Thus $ht_xh^{-1} = t_{\hat{h}(x)}$.

By the definition we have also $T^{-1} = T$, i.e. $t_x^{-1} = t_z$ for every $x \in T$, where $z = \hat{t}_z(1) = \hat{t}_x^{-1}(1) = x \setminus 1$. Thus $t_x^{-1} = t_{x \setminus 1}$. \square

Lemma 10. Let the conditions of Lemma 8 hold. If T is a gyrotransversal in the group G by a subgroup H , then the following conditions are equivalent:

1. the set P is a gyrotransversal in the group G by a subgroup H ,
2. $hh_{(x)}h^{-1} = h_{(\hat{h}(x))}$ and $h_{(x)}^{-1} = h_{(x \setminus 1)}$ for every $h \in H$, $x \in E$.

Proof. 1. \implies 2. Let the conditions of the present Lemma hold and let P be a gyrotransversal in the group G by its subgroup H . Then, by the definition, for $h \in H$ we have $hPh^{-1} \subseteq P$ and $P^{-1} = P$, which implies $ht_xh_{(x)}h^{-1} = t_uh_{(u)}$ for all $h \in H$, $x \in E$ and some $u \in E$. Thus

$$u = \hat{t}_u(1) = \hat{t}_u \hat{h}_{(u)}(1) = \hat{h} \hat{t}_x \hat{h}_{(x)} \hat{h}^{-1}(1) = \hat{h} \hat{t}_x(1) = \hat{h}(x).$$

Thus the previous equation can be rewritten in the form $ht_x h(x) h^{-1} = t_{\hat{h}(x)} h_{(\hat{h}(x))}$ and, in the consequence, in the form

$$t_{\hat{h}(x)}^{-1} ht_x h^{-1} = h_{(\hat{h}(x))} h_{(\hat{h}(x))}^{-1} h^{-1}. \quad (12)$$

As the set T is a gyrotransversal in the group G by the subgroup H , so, by Lemma 9, $ht_x h^{-1} = t_{\hat{h}(x)}$ for $h \in H$ and $x \in E$. Hence (12) has the form $e = h_{(\hat{h}(x))} h_{(\hat{h}(x))}^{-1} h^{-1}$, i.e. $hh(x)h^{-1} = h_{(\hat{h}(x))}$, which proves the first condition of 2.

To prove the second, observe that $P^{-1} = P$ implies $(t_x h(x))^{-1} = t_w h(w)$ for $x \in E$, where

$$w = \hat{t}_w(1) = \hat{t}_w \hat{h}_{(w)}(1) = (\hat{t}_x \hat{h}_{(x)})^{-1}(1) = \hat{h}_{(x)}^{-1} \hat{t}_x^{-1}(1) = \hat{h}_{(x)}^{-1}(x \setminus 1).$$

This means that the equation $(t_x h(x))^{-1} = t_w h(w)$ can be written in the form $h_{(x)}^{-1} t_x^{-1} = t_{\hat{h}_{(x)}^{-1}(x \setminus 1)} h_{(\hat{h}_{(x)}^{-1}(x \setminus 1))}$, i.e. in the form

$$h_{(\hat{h}_{(x)}^{-1}(x \setminus 1))} = t_{\hat{h}_{(x)}^{-1}(x \setminus 1)}^{-1} h_{(x)}^{-1} t_x^{-1} = (t_{\hat{h}_{(x)}^{-1}(x \setminus 1)}^{-1} h_{(x)}^{-1} t_{x \setminus 1} h(x)) h_{(x)}^{-1} t_{x \setminus 1}^{-1} t_x^{-1}.$$

This together with $ht_x h^{-1} = t_{\hat{h}(x)}$ gives $t_{\hat{h}_{(x)}^{-1}(x \setminus 1)}^{-1} h_{(x)}^{-1} t_{x \setminus 1} h(x) = e$, i.e. $h_{(\hat{h}_{(x)}^{-1}(x \setminus 1))} = h_{(x)}^{-1} t_{x \setminus 1}^{-1} t_x^{-1}$, which by $hh(x)h^{-1} = h_{(\hat{h}(x))}$ implies the equation $h_{(\hat{h}_{(x)}^{-1}(x \setminus 1))} = h_{(x)}^{-1} h_{(x \setminus 1)} h(x)$.

So we can write the equation $h_{(\hat{h}_{(x)}^{-1}(x \setminus 1))} = h_{(x)}^{-1} t_{x \setminus 1}^{-1} t_x^{-1}$ in the form $h_{(x)}^{-1} h_{(x \setminus 1)} h(x) = h_{(x)}^{-1} t_{x \setminus 1}^{-1} t_x^{-1}$, i.e. $t_x t_{x \setminus 1} h_{(x \setminus 1)} h(x) = e$.

Since the set T is a gyrotransversal in the group G by a subgroup H , by Lemma 9, for every $x \in E$ we have $t_x^{-1} = t_{x \setminus 1}$, which together with $t_x t_{x \setminus 1} h_{(x \setminus 1)} h(x) = e$ implies $h_{(x \setminus 1)} h(x) = e$. Hence $h_{(x)}^{-1} = h_{(x \setminus 1)}$. This proves the second condition of 2.

2. \implies 1. Let the conditions of Lemma 8 hold. If $hh(x)h^{-1} = h_{(\hat{h}(x))}$ and $h_{(x)}^{-1} = h_{(x \setminus 1)}$ for all $h \in H$, $x \in E$, then, by Lemma 9, for every $h \in H$ and $x \in E$ we have

$$hp_x h^{-1} = ht_x h(x) h^{-1} = (ht_x h^{-1})(hh(x)h^{-1}) = t_{\hat{h}(x)} h_{(\hat{h}(x))} = p_{\hat{h}(x)},$$

i.e. $hPh^{-1} \subseteq P$. Moreover, by Lemma 9, for every $x \in E$ we have also

$$\begin{aligned}
p_x^{-1} &= (t_x h_{(x)})^{-1} = h_{(x)}^{-1} t_x^{-1} = h_{(x \setminus 1)} t_{x \setminus 1} = \\
&= h_{(x \setminus 1)} t_{x \setminus 1} h_{(x \setminus 1)}^{-1} h_{(x \setminus 1)} = t_{\hat{h}_{(x \setminus 1)}(x \setminus 1)} h_{(x \setminus 1)} = \\
&= t_{\hat{h}_{(x \setminus 1)}(x \setminus 1)} h_{(\hat{h}_{(x \setminus 1)}(x \setminus 1))} h_{(\hat{h}_{(x \setminus 1)}(x \setminus 1))}^{-1} h_{(x \setminus 1)} = \\
&= t_{\hat{h}_{(x \setminus 1)}(x \setminus 1)} h_{(\hat{h}_{(x \setminus 1)}(x \setminus 1))} h_{(x \setminus 1)} h_{(x \setminus 1)}^{-1} h_{(x \setminus 1)}^{-1} h_{(x \setminus 1)} = \\
&= t_{\hat{h}_{(x \setminus 1)}(x \setminus 1)} h_{(\hat{h}_{(x \setminus 1)}(x \setminus 1))} = p_{\hat{h}_{(x \setminus 1)}(x \setminus 1)} \in P.
\end{aligned}$$

This together with $hPh^{-1} \subseteq P$ proves that set P is a gyrotransversal in the group G by a subgroup H . \square

5. Examples

Using propositions that are proved in the previous section, we will demonstrate some methods of construction of A_l -loops by the help of groups and A_l -loops.

Lemma 11. *If K is a group, $\text{Inn}(K)$ the group of its inner automorphisms, $M = K \times \text{Inn}(K)$ the semidirect product of K and $\text{Inn}(K)$, then the set $D = \{(x, \alpha_{a_x}) \mid x \in K\}$, where $a_x \in K$ are the indexes depended on $x \in K$, is a left transversal in the group M by a subgroup $H = \text{Inn}(K)$. Moreover, if $\alpha_u(a_x) = a_{\alpha_u(x)}$ for every $x, u \in K/Z(K)$, where $Z(K)$ is the center of K , then the system $\langle K, \overset{(D)}{\cdot}, 1 \rangle$ is an A_l -loop.*

Proof. Let the conditions of the Lemma hold. Because $\text{Inn}(K) \subseteq \text{Aut } K$, then for the group transversal $K_0 = \{(x, id) \mid x \in K\}$ in the group M by subgroup $H = \text{Inn}(K)$ any weak derivation of group $\langle K, \overset{(K)}{\cdot}, 1 \rangle$ is a weak automorphic derivation. According to Corollary 5, the system $\langle K, \overset{(D)}{\cdot}, 1 \rangle$ is an A_l -loop if $\alpha_u \alpha_{a_x} \alpha_u^{-1} = \alpha_{a_{\alpha_u(x)}}$ for $x \in K$, $\alpha_u \in \text{Inn}(K)$.

This shows that for every $x, u, y \in K$ holds $\alpha_u \alpha_{a_x} \alpha_u^{-1}(y) = \alpha_{a_{\alpha_u(x)}}(y)$. Therefore

$$\begin{aligned}
(ua_x u^{-1})y(ua_x^{-1} u^{-1}) &= \alpha_u(a_x u^{-1} y u a_x^{-1}) = \alpha_u \alpha_{a_x}(u^{-1} y u) = \\
&= \alpha_u \alpha_{a_x} \alpha_u^{-1}(y) = \alpha_{a_{\alpha_u(x)}}(y) = a_{\alpha_u(x)} y a_{\alpha_u(x)}^{-1}.
\end{aligned}$$

Hence $\alpha_u(a_x) y (\alpha_u(a_x))^{-1} = a_{\alpha_u(x)} y a_{\alpha_u(x)}^{-1}$ and $\alpha_{\alpha_u(a_x)} = \alpha_{a_{\alpha_u(x)}}$.

So, if $\alpha_u(a_x) = a_{\alpha_u(x)}$ holds, the system $\langle K, \overset{(D)}{\cdot}, 1 \rangle$ is an A_l -loop. \square

Corollary 6. *Let the conditions of Lemma 11 hold. If $\alpha_u(a_x) = a_{\alpha_u(x)}$, then $a_x \in C_K(x)$ for every $x \in K$, where $C_K(x)$ is the centralizer of x in the group K .*

Proof. It follows from $\alpha_u(a_x) = a_{\alpha_u(x)}$ for $u = x$. \square

Remark 4. In the case $a_x = x$ we obtain so-called *diagonal transversal* $D = \{(x, \alpha_x) | x \in K\}$ investigated in [4].

Remark 5. For $a_x = x^m$, where $m \in Z - \{0, 1\}$ is fixed, we obtain the *generalized diagonal transversals* $D = \{(x, \alpha_x^m) | x \in K\}$ described in [12].

Now we will demonstrate the method of constructing of A_l -loops by the help of A_l -loop L with nontrivial right nucleus $N_r(L)$.

Lemma 12. *Let the conditions of Lemma 8 hold. If $\hat{h}_{(x)} = l_{x, x \cdot c_0}^{(T)}$, where $c_0 \in N_r(\langle E, \cdot, 1 \rangle)$, $c_0 \neq 1$, then the system $\langle E, \cdot, 1 \rangle$ is an A_l -loop.*

Proof. Since the system $\langle E, \cdot, 1 \rangle$ is an A_l -loop, then

$$\hat{h}_{(x)} = l_{x, x \cdot c_0}^{(T)} \in LI(\langle E, \cdot, 1 \rangle) \subseteq Aut(\langle E, \cdot, 1 \rangle), \quad (13)$$

i.e. the weak derivation of A_l -loop $\langle E, \cdot, 1 \rangle$ onto left loop $\langle E, \cdot, 1 \rangle$ is a weak automorphic derivation. Moreover, in view of 1), Lemma 8 and (13) we obtain $l_{a, b}^{(P)} = \hat{h}_{(a)}^{-1} l_{a, \hat{h}_{(a)}(b)}^{(T)} \hat{h}_{(a)} \hat{h}_{(b)} \in LI(\langle E, \cdot, 1 \rangle)$ for every $a, b \in E$, i.e.

$$LI(\langle E, \cdot, 1 \rangle) \subseteq LI(\langle E, \cdot, 1 \rangle). \quad (14)$$

But $c_0 \in N_r(\langle E, \cdot, 1 \rangle)$. Then $l_{a, b}^{(T)}(c_0) = c_0$ for every $a, b \in E$. So $\alpha(c_0) = c_0$ for every $\alpha \in LI(\langle E, \cdot, 1 \rangle)$. Then, by (7) and (14), for every $x \in E$ and $\alpha \in LI(\langle E, \cdot, 1 \rangle)$ we obtain:

$$\begin{aligned} \alpha \hat{h}_{(x)} \alpha^{-1} &= \alpha l_{x, x \cdot c_0}^{(T)} \alpha^{-1} = \alpha \hat{t}_{x \cdot c_0}^{-1} \hat{t}_x \hat{t}_{x \cdot c_0} \alpha^{-1} = \\ &= (\alpha \hat{t}_{x \cdot c_0}^{-1} \alpha^{-1}) (\alpha \hat{t}_x \alpha^{-1}) (\alpha \hat{t}_{x \cdot c_0} \alpha^{-1}) = \\ &= \hat{t}_{\alpha(x) \cdot c_0}^{-1} \hat{t}_{\alpha(x)} \hat{t}_{\alpha(x) \cdot c_0} = \hat{t}_{\alpha(x)}^{-1} \hat{t}_{\alpha(x)} \hat{t}_{\alpha(x) \cdot c_0} = \\ &= l_{\alpha(x), \alpha(x) \cdot c_0}^{(T)} = l_{\alpha(x), \alpha(x)}^{(T)} \alpha(c_0) = l_{\alpha(x), \alpha(x)}^{(T)} = \hat{h}_{(\alpha(x))}. \end{aligned}$$

This, by 2) of Lemma 8, proves that $\langle E, \cdot^{(P)}, 1 \rangle$ is an A_l -loop. \square

Remark 6. The set $\{h_{(x)}\}_{x \in E}$ may be chosen in the another way. For example $\hat{h}_{(x)} = l_{x, c_0}^{(T)} \cdot x$, or, in the general case $\hat{h}_{(x)} = l_{R_1(x, c_1), R_2(x, c_2)}^{(T)}$, where R_1, R_2 are terms of two variables on E . If $c_1, c_2 \in N_r(\langle E, \cdot^{(T)}, 1 \rangle)$, then the system $\langle E, \cdot^{(P)}, 1 \rangle$ is an A_l -loop.

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